

## AB Allen-Bradley

## Power Eex:

700S High Performance AC Drives and
700H Adjustable Frequency AC Drives

Frame 9 ( 132 -160 KW / 200-250 HP)

Hardware Service Manual

Solid state equipment has operational characteristics differing from those of electromechanical equipment. Safety Guidelines for the Application, Installation and Maintenance of Solid State Controls (Publication SGI-1.1 available from your local Rockwell Automation sales office or online at http:// www.ab.com/manuals/gi) describes some important differences between solid state equipment and hard-wired electromechanical devices. Because of this difference, and also because of the wide variety of uses for solid state equipment, all persons responsible for applying this equipment must satisfy themselves that each intended application of this equipment is acceptable.

In no event will Rockwell Automation, Inc. be responsible or liable for indirect or consequential damages resulting from the use or application of this equipment.

The examples and diagrams in this manual are included solely for illustrative purposes. Because of the many variables and requirements associated with any particular installation, Rockwell Automation, Inc. cannot assume responsibility or liability for actual use based on the examples and diagrams.

No patent liability is assumed by Rockwell Automation, Inc. with respect to use of information, circuits, equipment, or software described in this manual.

Reproduction of the contents of this manual, in whole or in part, without written permission of Rockwell Automation, Inc. is prohibited.

Throughout this manual, when necessary we use notes to make you aware of safety considerations.


WARNING: Identifies information about practices or circumstances that can cause an explosion in a hazardous environment, which may lead to personal injury or death, property damage, or economic loss.

Important: Identifies information that is critical for successful application and understanding of the product.


ATTENTION: Identifies information about practices or circumstances that can lead to personal injury or death, property damage, or economic loss. Attentions help you:

- identify a hazard
- avoid the hazard
- recognize the consequences


Shock Hazard labels may be located on or inside the equipment (e.g., drive or motor) to alert people that dangerous voltage may be present.

Burn Hazard labels may be located on or inside the equipment (e.g., drive or motor) to alert people that surfaces may be at dangerous temperatures.
Important User Information ..... 1-2
Preface Overview
Who Should Use this Manual? ..... P-1
What is in this Manual ..... P-1
What is Not in this Manual ..... P-2
Reference Materials ..... P-2
Understanding Manual Conventions ..... P-3
Additional Support Available on Internet ..... P-3
General Precautions ..... P-4
Chapter 1 Troubleshooting and Error Codes
Creating Fault Reports ..... 1-2
Addressing 700S Hardware Faults ..... 1-2
Addressing 700H Hardware Faults ..... 1-3
Diagnostic Procedures by Symptom ..... 1-5
Chapter 2 Component Test Procedures
Forward Biased Diode Tests for Major Power Components ..... 2-1
Checking Rectifying Module ..... 2-4
Checking the Main Fan ..... 2-7
Checking Capacitors ..... 2-8
Checking AC-Choke ..... 2-9
Checking Terminals ..... 2-10
Chapter 3 Access Procedures
Torque Specifications ..... 3-1
Opening Drive ..... 3-4
Removing the DPI / HIM Assembly ..... 3-6
Removing 700S Control Assembly ..... 3-8
Removing the 700S Voltage Feedback Circuit Board. ..... 3-10
Removing the 700S Power Interface Circuit Board ..... 3-12
Removing the 700H I/O Boards and Control Assembly ..... 3-14
Removing the 700H Fiber Optic Adapter Board ..... 3-15
Removing the Control Frame and Cross Plate ..... 3-17
Removing the EMC-Protection Plate ..... 3-20
Removing the Power Module ..... 3-23
Removing the Rectifying Module ..... 3-27
Removing the Main Fan ..... 3-32
Removing the Fan Power Supply ..... 3-34
Removing Capacitors ..... 3-38
Removing the AC-Choke ..... 3-40
Chapter $4 \quad$ Start-Up After Repair
Loading the 700H EEPROM. ..... 4-1
Before Applying Power to the Drive ..... 4-2
Testing with the External DC Power Supply Without Load (Optional) ..... 4-4
Testing Without a Motor ..... 4-5
Performing the Power Circuit Diagnostic Test on a 700S ..... 4-5
Testing With the Motor ..... 4-6
Appendix A Service Tools and Equipment
Software Tools ..... A-1
Service tools ..... A-1
Appendix B Schematics
put Conditioning Circuitry for Drives with AC Input ..... B-1
Power Circuitry for 700S Drives with AC Input ..... B-2
Power Circuitry for 700S Drives with DC Input ..... B-3
Power Circuitry for 700 H Drives with AC Input ..... B-4
Power Circuitry for 700H Drives with DC Input. ..... B-5
Circuit Board Connections for 700S Drives ..... B-6
Circuit Board Connections for 700H Drives ..... B-7
Fan Power Supply Connections ..... B-8
Appendix C Disassembly / Assembly Diagrams
700S 261A / 300A Mechanical Construction ..... C-2
700H 261A / 300A Mechanical Construction ..... C-3
Cross Plate (terminals) and Internal Fan ..... C-4
EMC-Protection Plate ..... C-5
Capacitor Sub-Assembly ..... C-6
Fan Sub-Assembly ..... C-7
Control Bracket ..... C-8
Rectifying Module ..... C-9
Power Module ..... C-10
Key to ID Numbers ..... C-11

## Overview

## Who Should Use this Manual?

This manual is intended for qualified service personnel responsible for troubleshooting and repairing high power PowerFlex 700S and 700H AC Drives. You should have previous experience with, and basic understanding of, electrical terminology, procedures, required troubleshooting equipment, equipment protection procedures and methods, and safety precautions.

This manual contains hardware service information for Frame 9 PowerFlex 700 S and 700 H drives only. Verify that you are working on a Frame 9 drive by checking the data nameplate on the Control Frame. The frame number is printed just above the serial number.


## What is Not in this Manual

Reference Materials

This manual does not contain in depth fault information for troubleshooting. That information is available in publications 20C-PM001, Programming Manual - PowerFlex 700H Adjustable Frequency AC Drive, PFLEX-IN006, Installation Instructions - PowerFlex 700S and 700H Adjustable Frequency AC Drive and 20D-UM001, User Manual - PowerFlex 700S High Performance AC Drive.

Allen-Bradley publications are available on the internet at www.rockwellautomation.com/literature.

The following publications provide general drive information.

| Title | Publication |
| :--- | :--- |
| Wiring and Grounding Guide, (PWM) AC Drives | DRIVES-IN001... |
| Safety Guidelines for the Application, Installation and Maintenance of <br> Solid State Control | SGI-1.1 |
| A Global Reference Guide for Reading Schematic Diagrams | $0100-2.10$ |
| Guarding Against Electrostatic Damage | $8000-4.5 .2$ |

The following publications provide specific PowerFlex drive information.

| Title | Publication |
| :--- | :--- |
| Programming Manual - PowerFlex 700H AC Drive | 20C-PM001... |
| User Manual - PowerFlex 700S High Performance Drive | 20D-UM001... |
| Installation Instructions - Hi-Resolution Feedback Option Card for <br> PowerFlex 700S Drives | 20D-IN001... |
| Installation Instructions - Multi Device Interface Option for PowerFlex <br> $700 S$ <br> Drives | $20 \mathrm{D}-\mathrm{IN004} \mathrm{\ldots}$ |
| Installation Instructions - Main Control Board PowerFlex 700S Drives | 20D-IN005... |
| Installation Instructions - Control Assembly Cover for PowerFlex 700S <br> Drives | 20D-IN006... |
| Installation Instructions - PowerFlex 700S and 700H Drives | PFLEX-IN006... |
| Reference Manual - PowerFlex Adjustable Frequency Drive, (Volume <br> $1-70 ~ \& ~ 700) ~$ | PFLEX-RM001... |
| Reference Manual - PowerFlex Adjustable Frequency Drive, (Volume <br> $2-700 S)$ | PFLEX-RM002... |

The following publications provide information that is necessary when applying the DriveLogix Controller.

| Title | Publication |
| :--- | :--- |
| User Manual - DriveLogix System | 20D-UM002... |
| Installation Instructions - DriveLogix Controller | $20 \mathrm{D}-$ IN002... |
| Installation Instructions - Memory Expansion for DriveLogix Controller | $20 \mathrm{D}-$ IN007... |
| ControlNet Daughtercard Installation Instructions | $1788-$ IN002... |
| ControlNet Daughtercard Installation Instructions | $1788-$ IN005... |

## Understanding Manual

## Conventions

Terms
The following words are used throughout the manual to describe an action:

| Word | Meaning |
| :--- | :--- |
| Can | Possible, able to do something |
| Cannot | Not possible, not able to do something |
| May | Permitted, allowed |
| Must | Unavoidable, you must do this |
| Shall | Required and necessary |
| Should | Recommended |
| Should Not | Not recommended |

## Cross References

"Figure 2.2 on page 2-6" is a cross reference to figure 2.2 on page 5 of Chapter 2.
"Figure C. 1 on page $\mathrm{C}-2$ " is a cross reference to figure C .1 on page 2 of Appendix C.

Additional troubleshooting information and software tools are available on the Allen-Bradley Drives Support Website (http://www.ab.com/support/ abdrives/).

## General Precautions

## Class 1 LED Product

$\triangle$
ATTENTION: Hazard of permanent eye damage exists when using optical transmission equipment. This product emits intense light and invisible radiation. Do not look into module ports or fiber-optic cable connectors.

## $\triangle$

ATTENTION: This drive contains ESD (Electrostatic Discharge) sensitive parts and assemblies. Static control precautions are required when installing, testing, servicing or repairing this assembly. Component damage may result if ESD control procedures are not followed. If you are not familiar with static control procedures, reference A-B publication 8000-4.5.2, "Guarding Against Electrostatic Damage" or any other applicable ESD protection handbook.


ATTENTION: An incorrectly applied or installed drive can result in component damage or a reduction in product life. Wiring or application errors, such as, undersizing the motor, incorrect or inadequate AC supply, or excessive ambient temperatures may result in malfunction of the system.


ATTENTION: Only qualified personnel familiar with high power PowerFlex 700S and 700H Drives and associated machinery should plan or implement the installation, start-up and subsequent maintenance of the system. Failure to comply may result in personal injury and/or equipment damage.


ATTENTION: To avoid an electric shock hazard, verify that the voltage on the bus capacitors has discharged before performing any work on the drive. Measure the DC bus voltage at the DC+ \& DC- terminals. The voltage must be zero.


ATTENTION: Potentially fatal voltages may result from improper usage of an oscilloscope and other test equipment. The oscilloscope chassis may be at a potentially fatal voltage if not properly grounded. If an oscilloscope is used to measure high voltage waveforms, use only a dual channel oscilloscope in the differential mode with X 100 probes. It is recommended that the oscilloscope be used in the A minus B Quasi-differential mode with the oscilloscope chassis correctly grounded to an earth ground.

## Troubleshooting and Error Codes



ATTENTION: To avoid an electric shock hazard, ensure that all power to the drive has been removed before performing the following.

ATTENTION: To avoid an electric shock hazard, verify that the voltage on the bus capacitors has discharged before performing any work on the drive. Measure the DC bus voltage at the DC+ \& DC- terminals. The voltage must be zero.


ATTENTION: HOT surfaces can cause severe burns. Do not touch the heatsink surface during operation of the drive. After disconnecting power allow time for cooling.


ATTENTION: This drive contains ESD (Electrostatic Discharge) sensitive parts and assemblies. Static control precautions are required when installing, testing, servicing or repairing this assembly. Component damage may result if ESD control procedures are not followed. If you are not familiar with static control procedures, reference A-B publication 8000-4.5.2, "Guarding Against Electrostatic Damage" or any other applicable ESD protection handbook.

# Creating Fault Reports 

Clear and complete fault reports are critical for analysis and repair of modules returned to the factory.

At a minimum perform, and record the following:

- Record the contents of the fault queue (faults and times of occurrence)
- Make record of any burn marks on the rectifying module, DC-capacitors, inverter bridge, charging resistors, balancing/precharging resistors, printed circuit boards, bus bars, cabling and fiber-optic cabling
- Make record of any liquid and condensation marks on printed circuit boards, components and mechanical parts
- Make record of the amount of dust and other additional particles on drive and drive components
- Make record of any mechanical damage to the drive and drive components
- Record the size and type of main fuses
- Record any other important marks and damage

Addressing 700S Hardware Faults
\(\left.$$
\begin{array}{l|l|l|l}\hline \text { Fault } & \text { No. } & \text { Description } & \text { Action (if appropriate) } \\
\hline \text { HiHp In PhaseLs } & 65 & \begin{array}{l}\text { AC Input Phase Loss - AC voltage is } \\
\text { not present on one or two input } \\
\text { phases. }\end{array} & \begin{array}{l}\text { 1. Check for voltage on each } \\
\text { input phase } \\
\text { 2. Check the status of each } \\
\text { external input fuses }\end{array} \\
\hline \text { HiHp Bus Com Dly } & 66 & \begin{array}{l}\text { Bus Communication Time Delay - the } \\
\text { processor has not received proper } \\
\text { periodic feedback information. }\end{array} & \begin{array}{l}\text { Check fiber-optic connections } \\
\text { between the Power Interface } \\
\text { Circuit Board and Voltage } \\
\text { Feedback Circuit Board }\end{array} \\
\hline \text { HiHp Bus Link LS } & 67 & \begin{array}{l}\text { Bus Communication Link Loss - bus } \\
\text { communication between the Power } \\
\text { Interface Circuit Board and Voltage } \\
\text { Feedback Circuit Board has halted. }\end{array} & \begin{array}{l}\text { Check fiber-optic connections } \\
\text { between the Power Interface } \\
\text { Circuit Board and Voltage } \\
\text { Feedback Circuit Board }\end{array} \\
\hline \text { HiHp Bus CRC Er } & 68 & \begin{array}{l}\text { Bus Communication CRC Error - too } \\
\text { many Cycling Ring Checksum (CRC) } \\
\text { errors have occurred in the }\end{array} & \begin{array}{l}\text { Check fiber-optic connections } \\
\text { between the Power Interface } \\
\text { Communication bus. }\end{array}
$$ <br>

Feedback Circuit Board\end{array}\right]\)| CiHp Bus WtchDog |
| :--- |

\(\left.\left.$$
\begin{array}{l|l|l|l}\hline \text { Fault } & \text { No. } & \text { Description } & \text { Action (if appropriate) } \\
\hline \text { HiHp Drv OvrLoad } & 71 & \begin{array}{l}\text { Drive Overload - the circuit board on } \\
\text { the Power Module has detected an } \\
\text { overload. }\end{array} & \begin{array}{l}\text { Measure output current of the } \\
\text { drive. If the level is ever greater } \\
\text { than the maximum drive rated } \\
\text { output current level reduce the } \\
\text { load. If the levels are always } \\
\text { well below the drive rated } \\
\text { levels, then replace the power } \\
\text { module }\end{array} \\
\hline \text { HiHp PwrBd PrcEr } & 72 & \begin{array}{l}\text { Power Board Processor Error - a } \\
\text { microprocessor on the Power Board } \\
\text { has detected a communication error. }\end{array} & \begin{array}{l}\text { 1. Check fiber-optic } \\
\text { connections between the } \\
\text { Power Interface Circuit Board } \\
\text { and Voltage Feedback Circuit } \\
\text { Board }\end{array} \\
\text { 2. Check connections between } \\
\text { the Main Control Board and } \\
\text { the Power Interface Circuit } \\
\text { Board }\end{array}
$$\right\} \begin{array}{l}3. Replace the Voltage <br>

Feedback Circuit Board\end{array}\right\}\)| 4. Replace the Power Interface |
| :--- |
| Circuit Board |

Addressing 700H Hardware Faults

| Name | No. | Description | Action (if appropriate) |
| :--- | :--- | :--- | :--- |
| Power Loss | 3 | DC bus voltage remained below <br> [Power Loss Volts] for longer than <br> [Power Loss Time]. Enable/Disable <br> with [Fault Config 1]. For more <br> information refer to publication <br> 20C-PM001, Programming Manual - <br> PowerFlex 700H. | Monitor the incoming AC line for <br> low voltage or line power <br> interruption. |
| UnderVoltage | 4 | DC bus voltage fell below the <br> minimum value of 333V for 400/480V <br> drives and 461V for 600/ 690V drives. <br> Enable/Disable with [Fault Config 1]. | Monitor the incoming AC line for <br> low voltage or power <br> interruption. |
| For more information refer to <br> publication 20C-PM001, <br> Programming Manual - PowerFlex <br> 700H. |  |  |  |


| Name | No. | Description | Action (if appropriate) |
| :--- | :--- | :--- | :--- |
| OverVoltage | 5 | DC bus voltage exceeded maximum <br> value. | Monitor the AC line for high line <br> voltage or transient conditions. <br> Bus overvoltage can also be <br> caused by motor regeneration. <br> Extend the decel time or install <br> and external dynamic brake <br> option. |
| Input Phase | 10 | One input line phase missing. | Check user-supplied fuses <br> Check AC input line voltage. |
| OutPhasMissng | 11 | Zero current in one output motor <br> phase. | Check motor wiring. <br> Check motor for open phase. |
| Ground Fault | 13 | A current path to earth ground greater <br> than 25\% of drive rating. Ground fault <br> level is 50\% of the drive's heavy duty <br> current rating. The current must <br> appear for 800ms before the drive will <br> fault. | Check the motor and external <br> wiring to the drive output <br> terminals for a grounded <br> condition. |
| InverterFault | 14 | Hardware problem in the power <br> structure. | Cycle power. <br> Replace drive. |
| System Fault | 16 | Hardware problem exists in the power <br> structure. | Cycle power. <br> Replace drive. |
| Load Loss | 46 | 70 | One or more of the output transistors <br> were operating in the active region <br> instead of desaturation. This can be <br> caused by excessive transistor current <br> or insufficient base drive voltage. |
| Power Unit | Clear fault. |  |  |

Diagnostic Procedures by The following charts list drive symptom, symptom descriptions and Symptom recommended actions.

## Blown Input Fuses

Use this procedure when a drive clears any of its external circuit breaker or power fuses:


## No Output Voltage

Use this procedure when there is not voltage present at the drive output terminals, even though the drive indicates the motor is running:


## No HIM Display

Use this procedure when the HIM does not function:


## Over-Temperature Faults

Use this procedure to troubleshoot drive over-temperature faults (14-Inv Otemp Pend and 15 - Inv Otemp Trip in 700S or 8 - Heatsink OvrTemp and 9 - Trnsistr OvrTemp in 700H):


## Component Test Procedures



## ATTENTION: To avoid an electric shock hazard, ensure that all power to the drive has been removed before performing the following.

ATTENTION: To avoid an electric shock hazard, verify that the voltage on the bus capacitors has discharged before performing any work on the drive. Measure the DC bus voltage at the DC+ \& DC- terminals. The voltage must be zero.


ATTENTION: HOT surfaces can cause severe burns. Do not touch the heatsink surface during operation of the drive. After disconnecting power allow time for cooling.


ATTENTION: This drive contains ESD (Electrostatic Discharge) sensitive parts and assemblies. Static control precautions are required when installing, testing, servicing or repairing this assembly. Component damage may result if ESD control procedures are not followed. If you are not familiar with static control procedures, reference A-B publication 8000-4.5.2, "Guarding Against Electrostatic Damage" or any other applicable ESD protection handbook.

Forward Biased Diode Tests for Major Power Components

A forward biased diode test checks the semiconductor junctions between the terminals and measures the voltage drop across those junctions. To pass each test, the meter must beep once and display a voltage within the specification shown in the table. If the test finds a short, the meter will display. 000 and beep continuously. If the test finds an open circuit or reversed polarity, the meter will display ".0L" (zero load).

1. Remove power from the drive
2. Check for zero volts between $\mathrm{DC}+$ an $\mathrm{DC}-$
3. Remove the Connection cover, while referring to Opening Drive on page 3-4.
4. Disconnect the motor leads from the drive

## Forward Biased Diode Tests for Rectifying Module

Figure 2.1 Measurement Points for Forward Biased Diode Tests on Major Power Components

5. Perform forward biased diode tests, using a digital multimeter, on the points listed in Table 2.A on page 2-3 (on AC Three-Phase drives). If the Rectifying Module fails any of these tests, replace it (See Removing the Rectifying Module on page 3-27).
Table 2.A Forward Biased Diode Tests for Rectifying Module

| Meter Leads |  | Nominal meter reading |
| :---: | :---: | :---: |
| + | - |  |
| L1 | DC- | Value should gradually rise to 1.8 V |
| L2 | DC- |  |
| L3 | DC- |  |
| L1 | DC+/R+ ${ }^{(1)}$ | $0.450 \mathrm{~V} \pm 0.075 \mathrm{~V}$ |
| L2 | DC+/R+ |  |
| L3 | DC+/R+ |  |
| DC- | L1 | $0.335 \mathrm{~V} \pm 0.075 \mathrm{~V}$ |
| DC- | L2 |  |
| DC- | L3 |  |
| DC+/R+ ${ }^{(1)}$ | L1 | Value should gradually rise to 1.8 V |
| DC+/R+ | L2 |  |
| DC+/R+ | L3 |  |

(1) If the drive does not contain the brake chopper option, the $\mathrm{DC}+/ \mathrm{R}+$ terminal will be labeled DC+.

## Forward Biased Diode Tests for Output Power Module

6. Perform forward biased diode tests, using a digital multimeter, on the points listed in Table 2.B on page 2-3. If the Output Power Module fails any of these tests, replace it (See Removing the Power Module on page 3-23).

Table 2.B Forward Biased Diode Tests for Output Power Module

| Meter Leads |  | Nominal meter reading |
| :---: | :---: | :---: |
| + | - |  |
| T1 | DC- | Value should gradually rise to 1.8 V |
| T2 | DC- |  |
| T3 | DC- |  |
| T1 | DC+/R+ | $0.290 \mathrm{~V} \pm 0.075 \mathrm{~V}$ |
| T2 | DC+/R+ |  |
| T3 | DC+/R+ |  |
| DC- | T1 |  |
| DC- | T2 |  |
| DC- | T3 |  |
| DC+/R+ | T1 | Value should gradually rise to 1.8 V |
| DC+/R+ | T2 |  |
| DC+/R+ | T3 |  |

## Forward Biased Diode Tests for Brake Chopper

7. Perform forward biased diode tests, using a digital multimeter, on the points listed in Table 2.C on page 2-4 (on drives with Brake Choppers). If the Brake Chopper Assembly fails any of these tests, replace it.

Table 2.C Forward Biased Diode Tests for Brake Chopper Assembly

| Meter Leads |  |  |
| :--- | :--- | :--- |
| + | - | Nominal meter reading |
| R- | DC- | Value should gradually rise to 1.8 V |
| $R-$ | $D C+/ R+$ | $3.15 \mathrm{~V} \pm 0.075 \mathrm{~V}$ |
| $\mathrm{DC}-$ | $\mathrm{R}-$ | $0.36 \mathrm{~V} \pm 0.75 \mathrm{~V}$ |
| $\mathrm{DC}+/ \mathrm{R}+$ | $\mathrm{R}-$ | Value should gradually rise to 1.8 V |

Checking Rectifying Module 1. Remove power from the drive
2. Check for zero volts between $\mathrm{DC}+$ an $\mathrm{DC}-$
3. Remove the Connection cover, while referring to Opening Drive on page 3-4.
4. Remove the DPI/HIM Assembly, while referring to Removing the DPI / HIM Assembly on page 3-6.
5. Remove the 700S Control Assembly (on a 700S drive), while referring to Removing 700S Control Assembly on page 3-8.
6. Remove the 700S Voltage Feedback circuit board (on a 700S drive), while referring to Removing the 700S Voltage Feedback Circuit Board on page 3-10.
7. Remove the 700S Power Interface circuit board (on a 700S drive), while referring to Removing the 700S Power Interface Circuit Board on page 3-12.
8. Remove the 700 H Main Control board and enclosure (on a 700 H drive), while referring to Removing the 700 H Fiber Optic Adapter Board on page 3-15.
9. Referring to Removing the Control Frame and Cross Plate on page 3-17, remove the Control Frame and Cross Plate.
10.Referring to Removing the EMC-Protection Plate on page 3-20, remove the EMC-Protection Plate.
11.Visually inspect the pre-charging resistors. If pre-charging resistors are damaged:
A. Replace the Rectifying Module (See Removing the Rectifying Module on page 3-27).
B. Check capacitors, rectifiers and external connections for short-circuits. Referring to Forward Biased Diode Tests for Output Power Module on page 2-3, check the Output Power Module.

## Measurement of Rectifying Module

12.Disconnect connectors $\mathrm{X} 13, \mathrm{X} 12, \mathrm{X} 11$ and X 10 .
13.Perform resistance measurements, using a digital multimeter, on the points listed in Table 2.D on page 2-5 (on AC Three-Phase drives). These points are on the back of the X10, X11 and X12 plugs which you have disconnected from the board. If the Rectifying Module fails any of these tests, replace it (See Removing the Rectifying Module on page 3-27).

Table 2.D Rectifying Module Measurements

| Measurement points | Resistance |
| :--- | :--- |
| X10: red to X10: black |  |
| X11: red to X11: black | $18 \Omega \pm 1 \Omega$ |
| X12: red to X12: black |  |

## Checking the Rectifier Circuit Board

14. Connect 24 V power (from the test power supply) to X 13 : Pin 5 and 24 V Common to X13: Pin 1
15.Perform "DC Test Power Supply ON" tests in Table 2.E on page 2-6.
16.De-energize test power supply. Perform "DC Test Power Supply OFF" tests in Table 2.E on page 2-6.
17.If the results differ from measurements shown in Table 2.E on page 2-6, replace the Rectifying Module (See Removing the Rectifying Module on page 3-27).

Figure 2.2 Rectifying board layout and measurement points


Table 2.E Rectifying Board Forward Biased Diode Test Results

| Meter Leads |  | DC Test Power |
| :--- | :---: | :--- | :--- |
| Supply ON |  |  |$\quad$| DC Test Power |
| :--- |
| Supply OFF |

Important: Power supply polarity is critical during these tests. Reversing the polarity will damage components on the circuit board.

## Checking the Brake Chopper

These tests require a recommended multi-meter capable of measuring capacitance.
18. Disconnect the cable which connects the brake chopper to the Output Power Module connector X11.
19.Measure gate capacitance (gate to emitter) between the grey and white wires on the X11 plug.
20.Measure gate capacitance (gate to emitter) between the red and black wires on the X11 plug.

Important: Use correct polarity when you measure gate capacitance.
21.If measurement results are not similar to values in Table 2.F on page 2-7, replace both brake chopper and rectifying module (See Removing the Rectifying Module on page 3-27).

Table 2.F Proper Brake Chopper Measurements

| Meter Leads |  |  |
| :---: | :---: | :--- |
| + | - | Capacitance (+/- 20\%) |
| $\mathbf{X} 11$-grey | X11-white | 50 nF |
| X11-red | X11-black | 50 nF |

1. Remove power from the drive
2. Check for zero volts between DC+ an DC-
3. Remove the Connection cover, while referring to Opening Drive on page 3-4.
4. Remove the fan power supply cover, while referring to Removing the Fan Power Supply on page 3-34
5. Disconnect the fan motor from the output filter transformer (Refer to Fan Power Supply Connections on page B-8).
6. Measure the resistance of the fan windings. If the resulting measurements are not similar to those in Table 2.G on page 2-8, replace the fan (See Removing the Main Fan on page 3-32).

Table 2.G Correct Fan Measurements

| Connection Wires | Resistance $\pm \mathbf{5 \%}$ |
| :--- | :--- |
| Black-Brown | 62 |
| Brown-Blue | 36 |
| Blue-Black | 27 |

7. Disconnect capacitor from fan power supply.
8. Measure value of the start capacitor. If the resulting value does not equal $7 \mu \mathrm{~F}$, replace the capacitor (See Removing the Fan Power Supply on page 3-34).

Checking Capacitors
Important: This procedure requires special equipment and training. Only qualified and trained personnel should perform these procedures.

These tests require the recommended high voltage DC-power supply.

1. Test each capacitor with a DC-power supply. Recommended is to set DC power supply current limit $<50 \mathrm{~mA}$.
2. Connect the power supply's $\mathrm{DC}+$ to the drive's $\mathrm{DC}+$ terminal and the power supply's DC- to the drive's DC- terminal.
3. Set power supply voltage setting to zero.
4. Switch on the external DC power supply.
5. Slowly increase the external DC power supply output voltage to the drive's nominal DC bus voltage ( $1.35 \times$ Unity)

Example: 480v AC Nominal Voltage
$1.35 \mathrm{x} 480 \mathrm{v}=648 \mathrm{v}$
6. Monitor the current while testing.
7. Leakage current should be less than 3 mA when voltage has stabilized.
8. Abort test if current leakage is significantly higher when voltage has stabilized.
9. Decrease the DC power supply output voltage to zero. Wait until DC bus voltage has decreased to zero. Switch off the external DC power supply.
10.As a precaution, use a resistor to discharge each capacitor after testing. Use a proper resistor that can handle the discharging current.
11.If any capacitor has failed. Replace all the capacitors in the same series connection (See Removing Capacitors on page 3-38).

## Checking AC-Choke

1. Visually inspect the AC-Choke for burn marks.
2. Measure the resistance between and across each phase and from each phase to ground to verify that each phase is intact and not shorted to ground.
3. If the AC-Choke fails either inspection or tests, replace it (See Removing the AC-Choke on page 3-40).

## Checking Terminals

Check that cables L1 and L3 do not touch the ferrite ring.
If cables are touching the ferrite ring:

1. Loosen terminals L1 and L3.
2. Push cables L1 and L3 towards cable L2.
3. Tighten terminals, using torques specified in Torque Specifications on page 3-1.


## Access Procedures

$\triangle$
ATTENTION: To avoid an electric shock hazard, ensure that all power to the drive has been removed before performing the following.


ATTENTION: To avoid an electric shock hazard, verify that the voltage on the bus capacitors has discharged before performing any work on the drive. Measure the DC bus voltage at the DC+ \& DC- terminals. The voltage must be zero.


ATTENTION: HOT surfaces can cause severe burns. Do not touch the heatsink surface during operation of the drive. After disconnecting power allow time for cooling.

ATTENTION: Hazard of permanent eye damage exists when using optical transmission equipment. This product emits intense light and invisible radiation. Do not look into fiber-optic ports or fiber-optic cable connectors.


ATTENTION: This drive contains ESD (Electrostatic Discharge) sensitive parts and assemblies. Static control precautions are required when installing, testing, servicing or repairing this assembly. Component damage may result if ESD control procedures are not followed. If you are not familiar with static control procedures, reference A-B publication 8000-4.5.2, "Guarding Against Electrostatic Damage" or any other applicable ESD protection handbook.

The following table lists fastener torque specifications:

| Item | Screw | Torque Final |
| :---: | :---: | :---: |
| Connection Cover (mounting) | M4 x 8 Pozidrive $®$ | $\begin{aligned} & \hline 3 \mathrm{~N}-\mathrm{m} \\ & (27 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Power Cover (mounting) | (5) MM4 $\times 8$ Pozidrive | $\begin{aligned} & 3 \mathrm{~N}-\mathrm{m} \\ & (27 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Conduit Cover (mounting) | M4 x 8 Pozidrive | $\begin{aligned} & 3 \mathrm{~N}-\mathrm{m} \\ & (27 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| DPI / HIM Assembly Door | (\$) <br> M3 $\times 6$ Phillips® | $\begin{aligned} & 0.9 \mathrm{~N}-\mathrm{m} \\ & (8 \mathrm{lb} . \mathrm{in} .) \end{aligned}$ |
| DPI / HIM Assembly (mounting) | (1) M3 $\times 6$ Phillips | $\begin{aligned} & 0.9 \mathrm{~N}-\mathrm{m} \\ & (8 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Shield for 700S Voltage Feedback Circuit Board (mounting) | (1) M3 $\times 6$ Phillips | $\begin{aligned} & 0.9 \mathrm{~N}-\mathrm{m} \\ & (8 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| 700S Voltage Feedback Circuit Board (mounting) | M3 x 0.5 thread $-37 \mathrm{~mm} x$ 37 mm hex standoff | $\begin{aligned} & 0.9 \mathrm{~N}-\mathrm{m} \\ & (8 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |


| Item | Screw |  | Torque Final |
| :---: | :---: | :---: | :---: |
| 700S Power Interface Circuit Board (mounting) | (8) | M3 $\times 6$ Phillips | $\begin{aligned} & \hline 0.9 \mathrm{~N}-\mathrm{m} \\ & \text { (8 lb.in.) } \end{aligned}$ |
| 700H Control Board (mounting) |  | M3 x 5 Pozidrive | $\begin{aligned} & 0.9 \mathrm{~N}-\mathrm{m} \\ & (8 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| 700 H Control Board enclosure (mounting) |  | M4 x 8 Pozidrive M4 x 40 Pozidrive | $3 \mathrm{~N}-\mathrm{m}$ (27 lb.-in.) |
| 700H Fiber Optic Adapter bracket (mounting) | (98) | M4 x 8 Pozidrive | $\begin{aligned} & 3 \mathrm{~N}-\mathrm{m} \\ & (27 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| 700H Fiber Optic Adapter Board (mounting) | (78) | M4 x 8 Pozidrive | $\begin{aligned} & 0.9 \mathrm{~N}-\mathrm{m} \\ & (8 \mathrm{lb} . \mathrm{in} .) \end{aligned}$ |
| Control Frame (mounting) | 58) | M4 x 8 Pozidrive | 3 N-m ( $27 \mathrm{lb} .-\mathrm{in}$.) |
| Conduit (mounting) |  | M4 x 8 Pozidrive | $\begin{aligned} & 3 \mathrm{~N}-\mathrm{m} \\ & (27 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| MOV (mounting) | (i) | M4 x 30 Phillips | $\begin{aligned} & 3 \mathrm{~N}-\mathrm{m} \\ & (27 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Ground Wire on Cross Plate | (1) | M6 x 14 hexagonal screw | $4 \mathrm{~N}-\mathrm{m}$ ( $35 \mathrm{lb} .-\mathrm{in}$. ) |
| Cross Plate (mounting) | (98) | M4 x 8 Pozidrive | $\begin{aligned} & 3 \mathrm{~N}-\mathrm{m} \\ & (27 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| DC+, DC- and brake cable to DC-link | $\rangle$ | M8 nut | $\begin{aligned} & 14 \mathrm{~N}-\mathrm{m} \\ & (124 \mathrm{lb} . \mathrm{in} .) \end{aligned}$ |
| AC-choke (terminals) L1, L2, L3, A, B, C | (1) | M8 x 25 hexagonal screw | $\begin{aligned} & 17 \mathrm{~N}-\mathrm{m} \\ & (151 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| IGBT (terminals) | (1) | M8 x 20 hexagonal screw | $\begin{aligned} & 9 \mathrm{~N}-\mathrm{m} \\ & (80 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| DC+, DC-, and brake cable to top terminals | (1) | M8 x 20 hexagonal screw | $\begin{aligned} & 20 \mathrm{~N}-\mathrm{m} \\ & (177 \mathrm{lb} . \mathrm{in} .) \end{aligned}$ |
| EMI Protection Plate (mounting) | (54) | M4 x 8 Pozidrive | 3 N -m ( $27 \mathrm{lb} .-\mathrm{in}$. ) |
| DC- Bus Bars to rectifier/power busbars | $\text { ( } 78$ | M6 x 14 Pozidrive | $\begin{aligned} & 5 \mathrm{~N}-\mathrm{m} \\ & (44 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Rectifier/Power Module (upper mounting) |  | M5 x 10 Pozidrive | $\begin{aligned} & 4 \mathrm{~N}-\mathrm{m} \\ & (35 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Rectifier/Power Module (lower mounting) | 5 | M5 x 10 Pozidrive | $\begin{aligned} & 4 \mathrm{~N}-\mathrm{m} \\ & (35 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Rectifier (terminals) | (1) | M8 x 20 hexagonal screw | $\begin{aligned} & 9 \mathrm{~N}-\mathrm{m} \\ & (80 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Fan Power Supply Plate (mounting) | (78) | M4 x 8 Pozidrive | $\begin{aligned} & 3 \mathrm{~N}-\mathrm{m} \\ & (27 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Fan Assembly (top mounting) | (5) | M4 x 8 Pozidrive | $\begin{aligned} & 3 \mathrm{~N}-\mathrm{m} \\ & (27 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Fan Assembly (bottom mounting) | (98) | M4 x 8 Pozidrive | $\begin{aligned} & 3 \mathrm{~N}-\mathrm{m} \\ & (27 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Fan Power Supply Capacitor Bracket (mounting) | 58) | M4 x 8 Pozidrive | $3 \mathrm{~N}-\mathrm{m}$ (27 lb.-in.) |
| Fan Power Supply (mounting) | (58) | M4 x 8 Pozidrive | $\begin{aligned} & 1.8 \mathrm{~N}-\mathrm{m} \\ & (15 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Capacitor (-) Bus Bar | (5) | M6 x 16 Pozidrive | $\begin{aligned} & 4 \mathrm{~N}-\mathrm{m} \\ & (35 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Capacitor (+) Bus Bar | (5) | M6 x 14 Pozidrive | $\begin{aligned} & 4 \mathrm{~N}-\mathrm{m} \\ & (35 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Capacitor (+) Bus Bar with bush ring | (5) | M6 x 20 Pozidrive | $\begin{aligned} & 4 \mathrm{~N}-\mathrm{m} \\ & (35 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| DC+ and DC- cables to Bus Bars | (1) | M8 x 20 hexagonal screw | $\begin{aligned} & 10 \mathrm{~N}-\mathrm{m} \\ & (89 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |


| Item | Screw |  | Torque Final |
| :---: | :---: | :---: | :---: |
| Brake chopper（terminals） | 過 | M5 x 12 Pozidrive | $\begin{aligned} & 4 \mathrm{~N}-\mathrm{m} \\ & (35 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Brake chopper Bus Bar（terminal） | (1) | M8 x 20 hexagonal screw | $\begin{aligned} & 10 \mathrm{~N}-\mathrm{m} \\ & (89 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Rectifier（mounting） | 劳 | M6 x 20 Pozidrive | $\begin{aligned} & 5 \mathrm{~N}-\mathrm{m} \\ & (44 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Brake chopper（mounting） | 赲 | M6 x 14 Pozidrive | 5N－m <br> （ 44 lb ．－in．） |
| Rectifying board | (品) | M4 x 8 Pozidrive | $\begin{aligned} & 1.5 \mathrm{~N}-\mathrm{m} \\ & \text { (13 lb.-in.) } \end{aligned}$ |
| AC－choke（upper plate mounting） |  | M8 x 8 Pozidrive | $\begin{aligned} & 3 \mathrm{~N}-\mathrm{m} \\ & (27 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Control Bracket（mounting） | (品) | M4 x 8 Pozidrive | $\begin{aligned} & 3 \mathrm{~N}-\mathrm{m} \\ & (27 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| AC－choke（mounting） | 荧 | M5 x 10 Pozidrive | $\begin{aligned} & 4 \mathrm{~N}-\mathrm{m} \\ & (35 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| Motor and AC Line Terminals | $\rangle$ | M8 nut | $\begin{aligned} & 20 \mathrm{~N}-\mathrm{m} \\ & (177 \mathrm{lb} . \mathrm{in} .) \end{aligned}$ |
| Terminal Strip Assembly（mounting） | (然 | M5 x 10 Pozidrive | $\begin{aligned} & 4 \mathrm{~N}-\mathrm{m} \\ & (35 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |

Pozidrive® is a registered trademark of the Phillips Screw Company Phillips $®$ is a registered trademark of Phillips Screw Company

## Understanding Torque Figures in Assembly Diagrams

Icons and numbers in the assembly diagrams indicate how to tighten hardware：


## Opening Drive

## Opening

1. Remove power from drive.
2. Check for zero volts between DC+ and DC-.
3. Remove Connection cover

4. Remove Power cover



## Closing

The covers may be replaced and removed in any order.

## Removing the DPI / HIM <br> Assembly

## Removal

1. Remove power from drive.
2. Check for zero volts between $\mathrm{DC}+$ and DC -
3. Referring to Opening Drive on page $3-4$, remove the Power Cover from the drive.

Important: Before removing connections and wires, mark the connections and wires to avoid incorrect wiring during assembly.
4. Remove two screws from front of DPI / HIM assembly.

5. Open the door, which holds the DPI interface and HIM.
6. Unplug the DPI cable from X2 connector on the DPI Interface Circuit Board.

7. Unplug the cable from X 4 connector on the circuit board (on 700S drives only).
8. Remove four mounting screws and the assembly from the Control Frame.


## Installation

Install the DPI / HIM Assembly in reverse order of removal, while referring to Torque Specifications on page 3-1.

Removing 700S Control Assembly


1. Remove power from drive.
2. Check for zero volts between DC+ and DC-.
3. Referring to Opening Drive on page $3-4$, remove the Power Cover from the drive.

Important: Before removing connections and wires, mark the connections and wires to avoid incorrect wiring during assembly.
4. On the 700S control assembly, unplug I/O and SynchLink cables from the Main Control Board, unplug feedback wiring from feedback option card and unplug communication cables from Drivelogix controller.


ATTENTION: Hazard of permanent eye damage exists when using optical transmission equipment. This product emits intense light and invisible radiation. Do not look into SynchLink fiber-optic ports or SynchLink fiber-optic cable connectors.

Important: Minimum inside bend radius for SynchLink fiber-optic cable is 25.4 mm (1 in.). Any bends with a shorter inside radius can
permanently damage the fiber-optic cable. Signal attenuation increases with decreased inside bend radii.
5. Unplug J2 and J7 ribbon cables from the Main Control Board.
6. Loosen captive screw.
7. Swing Control Assembly away from drive.
8. Lift Control Assembly up and off of hinge.

## Installation

Install the 700S Control Assembly in reverse order of removal, while referring to Torque Specifications on page 3-1.

## Removing the 700S Voltage <br> Removal

## Feedback Circuit Board



1. Remove power from drive.
2. Check for zero volts between DC+ and DC-.
3. Referring to Opening Drive on page 3-4, remove the Power Cover from the drive.
4. Carefully disconnect fiber-optic cables from sockets J4 and J5 of the Voltage Feedback Circuit Board, and carefully set them aside.

| ATTENTION: Hazard of permanent eye damage exists when |
| :--- |
| using optical transmission equipment. This product emits intense |
| light and invisible radiation. Do not look into fiber-optic ports or |
| fiber-optic cable connectors. |

Important: Minimum inside bend radius for fiber-optic cable is 25.4 mm (1 in.). Any bends with a shorter inside radius can permanently
damage the fiber-optic cable. Signal attenuation increases with decreased inside bend radii.
5. Disconnect feedback cables from sockets J1 and J2 of the Voltage Feedback Circuit Board.
6. Remove the four screws which secure the clear plastic shield to the standoffs and remove the shield.
7. Remove the five standoffs which support the clear plastic shield and secure the Voltage Feedback Circuit Board to its mounting plate.
8. Remove the Voltage Feedback Circuit Board from its mounting plate.

## Installation

Install the Voltage Feedback Circuit Board in reverse order of removal, while referring to Torque Specifications on page 3-1.

## Removing the 700S Power Interface Circuit Board <br> Removal



1. Remove power from drive.
2. Check for zero volts between DC+ and DC-.
3. Referring to Opening Drive on page 3-4, remove the Power Cover from the drive.
4. Carefully disconnect the ribbon cables from sockets along the top side of the Power Interface Circuit Board, and carefully set them aside.
5. Carefully disconnect the fiber-optic cables from sockets along the right side of the circuit board, and carefully set them aside.

ATTENTION: Hazard of permanent eye damage exists when using optical transmission equipment. This product emits intense light and invisible radiation. Do not look into fiber-optic ports or fiber-optic cable connectors.

Important: Minimum inside bend radius for fiber-optic cable is 25.4 mm (1 in.). Any bends with a shorter inside radius can permanently
damage the fiber-optic cable. Signal attenuation increases with decreased inside bend radii.
6. Disconnect other cables from sockets of the circuit board, and set them aside.
7. Remove the five screws which secure the Power Interface Circuit Board to the Control Frame.
8. Remove the circuit board from the Control Frame.

## Installation

Install the 700S Power Interface Circuit Board in reverse order of removal, while referring to Torque Specifications on page 3-1.

Removing the 700H I/O
Boards and Control Assembly

## Removal

1. Remove power from drive.
2. Check for zero volts between DC+ and DC-.
3. Referring to Opening Drive on page 3-4, remove the Power Cover, Connection Cover and Conduit Cover from the drive.
4. Open the enclosure that contains the Control and I/O Boards and carefully unplug the DPI cable and any I/O cables.
5. Remove the I/O Boards from the Control Board and enclosure. Note the order of the boards and the keys which prevent placement of boards in incorrect slots.

Do not remove enclosure cover. Enclosure is illustrated without the cover for clarity.

6. Unplug the serial connection from X 7 of the Control Board.

7. Remove the three screws which secure the Control Assembly to the drive.

Do not remove enclosure cover. Enclosure is illustrated without the cover for clarity.

8. Remove the Control Assembly.

## Installation

Install the 700 H Control and I/O Boards in reverse order of removal, while referring to Torque Specifications on page 3-1.

Removing the 700 H Fiber Optic Adapter Board

## Removal

1. Remove power from drive.
2. Check for zero volts between DC+ and DC-.
3. Referring to Opening Drive on page $3-4$, remove the Power Cover, Connection Cover and Conduit Cover from the drive.
4. Referring to Removing the 700 H I/O Boards and Control Assembly on page 3-14, remove the I/O boards and Control Assembly.
5. Remove the Control Frame while referring to Removing the Control Frame and Cross Plate on page 3-17.
6. Remove the four screws which secure the Fiber Optic Adapter bracket to the drive.

7. Remove the Fiber Optic Adapter bracket.
8. Disconnect the control power cable from X2 of the Fiber Optic Adapter Board.

9. Carefully disconnect the fiber-optic cables from right side of the circuit board, and carefully set them aside.

$\triangle$
ATTENTION: Hazard of permanent eye damage exists when using optical transmission equipment. This product emits intense light and invisible radiation. Do not look into fiber-optic ports or fiber-optic cable connectors.

Important: Minimum inside bend radius for fiber-optic cable is 25.4 mm (1 in.). Any bends with a shorter inside radius can permanently damage the fiber-optic cable. Signal attenuation increases with decreased inside bend radii.
10.Remove the four screws which secure the Fiber Optic Adapter Board to the bracket.
11.Remove the Fiber Optic Adapter Board from the bracket.

## Installation

Install the 700 H Fiber Optic Adapter Board in reverse order of removal, while referring to Torque Specifications on page 3-1.

## Removing the Control Frame and Cross Plate

## Removal

1. Remove power from drive.
2. Check for zero volts between DC+ and DC-.
3. Referring to Opening Drive on page 3-4, remove the Power Cover, Connection Cover and Conduit Cover from the drive.
4. Referring to Removing the DPI / HIM Assembly on page 3-6, remove the DPI / HIM assembly.
5. If removing a Control Frame from a DC input drive with precharge interlock, disconnect the wiring from terminal strip X50.

Important: Before removing connections and wires, mark the connections and wires to avoid incorrect wiring during assembly.
6. If removing a Control Frame from a 700 S drive, remove the Power Interface and Voltage Feedback circuit boards (refer to Removing the 700S Voltage Feedback Circuit Board on page 3-10 and Removing the 700S Power Interface Circuit Board on page 3-12).
7. If removing a Control Frame from a 700 H drive, carefully disconnect the connections to the I/O boards and Control Assembly, and carefully set aside
8. Remove the DPI / HIM Assembly, while referring to Removing the DPI / HIM Assembly on page 3-6.
9. Remove eight screws which secure the Control Frame to the drive.
10.Remove the six screws which secure the Conduit to the drive.

11.Remove the Conduit from the drive.
12. Remove the Control Frame from the drive while carefully routing the cables and wires through the access hole of the Control Frame.
13.Disconnect the Cross Plate Fan (if present), MOV and ground wires.

| $($ | P2 <br> 3 N-m <br> ( $27 \mathrm{lb} .-\mathrm{in}$.) |
| :---: | :---: |



14. Remove three screws which hold Cross Plate to the drive.
15.Remove the Cross Plate.

## Installation

Install the Control Frame and Cross Plate in reverse order of removal, while referring to Torque Specifications on page 3-1.

Removing the
EMC-Protection Plate

## Removal

1. Remove power from drive.
2. Check for zero volts between DC+ and DC-.
3. Referring to Opening Drive on page 3-4, remove the Power Cover, Connection Cover and Conduit Cover from the drive.
4. Referring to Removing the DPI / HIM Assembly on page 3-6, remove the DPI / HIM assembly.
5. Referring to Removing the Control Frame and Cross Plate on page 3-17, remove the Control Frame and Cross Plate.
6. Disconnect the internal DC Bus wires from the DC Bus terminals at the top of the drive.

7. Disconnect the internal three-phase wiring from the AC choke (if present).

8. Disconnect the output cables from the top of the Power Module.

9. Remove four screws which secure the EMI-Protection Plate to the drive. Also remove the two screws which secure the common mode inductors.

10.Disconnect the fan which is mounted on the EMI-Protection Plate.
11.Remove the EMI-Protection Plate.

## Installation

Install the EMC-Protection Plate in reverse order of removal, while referring to Torque Specifications on page 3-1.

## Removing the Power Module Removal

1. Remove power from drive.
2. Check for zero volts between DC+ and DC-.
3. Referring to Opening Drive on page 3-4, remove the Power Cover, Connection Cover and Conduit Cover from the drive.
4. Referring to Removing the DPI / HIM Assembly on page 3-6, remove the DPI / HIM assembly.
5. Referring to Removing the Control Frame and Cross Plate on page 3-17, remove the Control Frame and Cross Plate.
6. Referring to Removing the EMC-Protection Plate on page 3-20, remove the EMC-Protection Plate.
7. Disconnect all of the cables from the Power Module circuit board.

8. Remove the six screws which connect the Power Module to the DC Bus bars.

9. Remove the three fastening screws at the top of the Power Module.
10.Loosen (4-5 turns), but do not remove the three fastening screws at the bottom of the Power Module.
11.Install the RT1 tool on the Power Module and remove the module from the drive.


## Installation

Install the Power Module in reverse order of removal, while referring to Torque Specifications on page 3-1.

## Removing the Rectifying Module

## Removal

1. Remove power from drive.
2. Check for zero volts between DC+ and DC-.
3. Referring to Opening Drive on page $3-4$, remove the Power Cover, Connection Cover and Conduit Cover from the drive.
4. Referring to Removing the DPI / HIM Assembly on page 3-6, remove the DPI / HIM assembly.
5. Referring to Removing the Control Frame and Cross Plate on page 3-17, remove the Control Frame and Cross Plate.
6. Referring to Removing the EMC-Protection Plate on page 3-20, remove the EMC-Protection Plate.
7. Remove the three-phase AC wiring from the Rectifying Module. Also remove the Brake Chopper Cable, if present.

8. Disconnect the cables from connectors on the Rectifying Module circuit board.

9. Remove the three screws which secure Rectifying Module circuit board to the Rectifying Module sub-assembly. Do not remove the screws at the top of the module which secure the conducting straps (that connect the circuit board to AC power from the AC Choke).

10.Remove the Rectifying Module circuit board.
11.Remove the six screws which connect the Rectifying Module to the DC Bus bars.

12.Remove the three fastening screws at the top of the Rectifying Module.
13.Loosen ( $4-5$ turns), but do not remove the three fastening screws at the bottom of the Rectifying Module.
14.Install the RT1 tool on the Rectifying Module and remove the module from the drive.


## Installation

Install the Rectifying Module in reverse order of removal, while referring to Torque Specifications on page 3-1.

Important: Before installing a new Rectifying Module, be sure to remove the circuit board. Mechanical interference with the RT1 tool could damage the new circuit board.

## Removing the Main Fan Removal

1. Remove power from drive.
2. Check for zero volts between DC+ and DC-.
3. Referring to Opening Drive on page $3-4$, remove the Connection Cover from the drive.
4. Remove the four rubber bushings which cover the screws which mount the fan assembly

5. Remove the screw which secures the fan power supply plate. Then lift and pull the plate away from the drive.

6. Disconnect the motor lead wires including the ground wire. Refer to Figure B. 8 on page B-8, when reconnecting these wires.
7. Check that the upper mounting bolts securely hold drive on the wall of the system enclosure. Remove lower mounting bolts from the bottom of the frame.
8. Loosen, but do NOT remove, four front screws (which are accessible through the holes vacated by the rubber bushings) so that the fan assembly can easily slide off. To loosen, but not remove these front screws, turn them 12 times.
9. Remove four screws from bottom of the frame. The fan plate should now easily slide down. If it does not, loosen the front screws another turn and attempt again. Continue loosening the screws until the fan plate slides easily from the drive.

Important: Do not attempt to force the fan plate from the drive. This may bend the fan.
10.Remove fan from fan plate. Refer to Figure C .6 on page $\mathrm{C}-7$.

## Installation

Install the fan in reverse order of removal, while referring to Torque Specifications on page 3-1. Refer to Figure B. 8 on page B-8, when reconnecting the fan and fan power supply.

## Removing the Fan Power

 Supply
## Removal

1. Remove power from drive.
2. Check for zero volts between DC+ and DC-
3. Referring to Opening Drive on page $3-4$, remove the Connection Cover from the drive.
4. Remove the screw which secures the fan power supply plate. Then lift and pull the plate away from the drive.

5. Disconnect the wires which run from the transformer to the power supply (X4 and X5 on the power supply). Refer to Figure B. 8 on page $\mathrm{B}-8$, when reconnecting these wires.
6. On the fuseholder/capacitor bracket disconnect the capacitor from the transformer. Disconnect the power supply cooling fan and the fuses.
7. Remove the screws which mount the fuseholder/capacitor bracket to the drive, and remove the bracket.

8. Disconnect the remaining cable from the power supply (X8 on the power supply).
9. Remove the screws which mount the power supply to the drive, and remove the power supply.

## Installation

1. Install the fan power supply and fuseholder/capacitor bracket in reverse order of removal, while referring to Torque Specifications on page 3-1.
2. Verify that dip switch $S 1$ is properly configured.

3. Install fan power supply plate.

## Removing Capacitors

Table 3.A Capacitor Sub-assembly Hardware

| Id. No. | Description |
| :--- | :--- |
| 42 | Screw M6 x14 Z4-1 (combination) |
| 44 | Screw M6 x16 Z4-1 (combination) |
| 45 | Screw M5x20 TX (combination) |
| 52 | Washer (straight) M8 SFS3738 |
| 53 | Washer (cone) M8 DIN679 |
| 54 | Screw hexagonal M8 X 20 |
| 112 | Cable DC+ |
| 114 | Cable DC- |

## Removal

1. Remove power from drive.
2. Check for zero volts between $\mathrm{DC}+$ and DC -
3. Referring to Opening Drive on page 3-4, remove the Connection Cover from the drive.
4. Referring to Removing the Control Frame and Cross Plate on page 3-17, remove the Control Frame and Cross Plate.
5. Remove terminal sub-assembly (Number 88 in Figure C. 1 on page C-2 or Figure C. 2 on page C-3)
6. Disconnect fiber-optic connectors $\mathrm{X} 7, \mathrm{X} 10$ and internal fan cable from power board.
7. Remove DC+ and DC- cables (Numbers 112 and 114).
8. Remove twelve (12) screws which connect the Output Power Module and Rectifying Module (if present) to the DC+ and DC- busbars.
9. Remove sixteen (16) screws (Numbers 42, 44 and 45) from capacitor terminals.

10. Remove busbars and insulators.

11.Remove screws which secure capacitors to drive.
12.Remove capacitors from drive.

## Installation

Install the capacitors in reverse order of removal, while referring to Torque Specifications on page 3-1.

Important: The screws in this sub-assembly vary in length. It is critical that you use the correct screws in the correct locations. Refer to Table 3.A on page 3-38.

## Removing the AC-Choke <br> Removal

1. Remove power from drive.
2. Check for zero volts between $\mathrm{DC}+$ and DC -
3. Referring to Opening Drive on page 3-4, remove the Connection Cover from the drive.
4. Referring to Removing the Control Frame and Cross Plate on page 3-17, remove the Control Frame and Cross Plate.
5. Disconnect the internal DC Bus wires from the DC Bus terminals at the top of the drive.

6. Remove nine (9) screws from upper plate.

7. Remove control bracket (Number 63 in Figure C. 1 on page C-2 or Figure C. 2 on page $\mathrm{C}-3$ )
8. Remove all cables from AC-choke terminals.

9. Remove eight (8) fastening screws from AC-choke.

10.Remove AC-choke from drive by using lifting lugs.

## Installation

Install the AC-choke in reverse order of removal, while referring to Torque Specifications on page 3-1.

## Start-Up After Repair

$\triangle$


#### Abstract

ATTENTION: Power must be applied to the drive to perform the following start-up procedure. Some of the voltages present are at incoming line potential. To avoid electric shock hazard or damage to equipment, only qualified service personnel should perform the following procedure. Thoroughly read and understand the procedure before beginning. If an event does not occur while performing this procedure, Do Not Proceed. Remove Power including user supplied control voltages. User supplied voltages may exist even when main AC power is not applied to then drive. Correct the malfunction before continuing.


Loading the 700H EEPROM
If you replace the Output Power Module or Control Board in a 700 H drive, you must load information about the Power Module or Control Board into the Power EEPROM. Contact Allen-Bradley Drives Technical Support for instructions and tools for performing this operation.

| Phone | United States/ | 1.262 .512 .8176 (7 AM - 6 PM CST) <br> Canada |
| :--- | :--- | :--- |
|  | Outside United | You can access the phone number for your country via |
| the Internet: |  |  |
| States/Canada |  |  |
|  |  | Go to http://www.ab.com <br> Click on Support (http:// <br> support.rockwellautomation.com/) <br> Under Contact Customer Support, click on Phone <br> Support |
| Internet | $\Rightarrow$ | Go to http://www.ab.com/support/abdrives/ |
| E-mail | $\Rightarrow$ | support@drives.ra.rockwell.com |

Be prepared to furnish the following information when you contact support:

- Product Catalog Number
- Product Serial Number
- Firmware Revision Level


## Before Applying Power to the Drive

1. Check for zero volts between DC+ and DC-
2. Perform forward biased diode tests, using a digital multimeter, on the

points listed in Table 4.A on page 4-3 to test the Rectifying Module (on AC Three-Phase drives). A forward biased diode test checks the semiconductor junctions between the terminals and measures the voltage drop across those junctions. To pass each test, the meter must beep ${ }^{(1)}$ once and display a voltage within the specification shown in the table. If the test finds a short, the meter will display .000 and beep continuously. If the test finds an open circuit or reversed polarity, the meter will display ". 0 L " (zero load). If the Rectifying Module fails any of these tests, replace it.
(1) Not all makes and models of digital multi-meters beep, consult documentation for your meter to determine how it indicates a positive result for the forward biased diode test and short circuit.

Table 4.A Forward Biased Diode Tests for Rectifying Module

| Meter Leads |  | Nominal meter reading |
| :---: | :---: | :---: |
| + | - |  |
| L1 | DC- | Value should gradually rise to 1.8 V |
| L2 | DC- |  |
| L3 | DC- |  |
| L1 | DC+/R+ | $0.450 \mathrm{~V} \pm 0.075 \mathrm{~V}$ |
| L2 | DC+/R+ |  |
| L3 | DC+/R+ |  |
| DC- | L1 | $0.335 \mathrm{~V} \pm 0.075 \mathrm{~V}$ |
| DC- | L2 |  |
| DC- | L3 |  |
| $\overline{\mathrm{DC}+/ \mathrm{R}+{ }^{(1)}}$ | L1 | Value should gradually rise to 1.8 V |
| DC+/R+ | L2 |  |
| DC+/R+ | L3 |  |

${ }^{(1)}$ If the drive does not contain the brake chopper option, the $\mathrm{DC}+/ \mathrm{R}_{+}$ terminal will be labeled $D C+$.
3. Perform forward biased diode tests, using a digital multimeter, on the points listed in Table 4.B to test the Output Power Module. If the Output Power Module fails any of these tests, replace it.

Table 4.B Forward Biased Diode Tests for Output Power Module

| Meter Leads |  | Nominal meter reading |
| :---: | :---: | :---: |
| + | - |  |
| T1 | DC- | Value should gradually rise to 1.8 V |
| T2 | DC- |  |
| T3 | DC- |  |
| T1 | DC+/R+ | $0.290 \mathrm{~V} \pm 0.075 \mathrm{~V}$ |
| T2 | DC+/R+ |  |
| T3 | DC+/R+ |  |
| DC- | T1 |  |
| DC- | T2 |  |
| DC- | T3 |  |
| DC+/R+ | T1 | Value should gradually rise to 1.8 V |
| DC+/R+ | T2 |  |
| DC+/R+ | T3 |  |

4. Perform forward biased diode tests, using a digital multimeter, on the points listed in Table 4.C to test the Brake Chopper Assembly (on drives with Brake Choppers). If the Brake Chopper Assembly fails any of these tests, replace it.

Table 4.C Forward Biased Diode Tests for Brake Chopper Assembly

| Meter Leads |  |  |
| :--- | :--- | :--- |
| + | Nominal meter reading |  |
| R | $\mathrm{DC}-$ | Value should gradually rise to 1.8 V |
| R | $\mathrm{DC}+/ \mathrm{R}+$ | $3.15 \mathrm{~V} \pm 0.075 \mathrm{~V}$ |
| $\mathrm{DC}-$ | R | $3.60 \mathrm{~V} \pm 0.75 \mathrm{~V}$ |
| $\mathrm{DC}+/ \mathrm{R}+$ | R | Value should gradually rise to 1.8 V |

## Testing with the External DC Power Supply Without Load (Optional)

This is a low current - low risk test for the Output Power Module and drive Control board. It requires the recommended high voltage DC-power supply.

1. Verify that the external DC power supply is de-energized
2. Connect the power supply's DC+ to the drive's DC+ terminal and the power supply's DC - to the drive's DC - terminal.
3. Set power supply voltage setting to zero.
4. Switch on the external DC power supply.
5. Slowly increase the external DC power supply output voltage to the drive's nominal DC bus voltage ( 1.35 x Unity)

Example: 480v AC Nominal Voltage

$$
\frac{3 \bullet \sqrt{2}}{\Pi} \cdot \mathrm{~V}=1.35 \times 480 \mathrm{~V}=648 \mathrm{~V}
$$

6. Measure the DC bus voltage and verify that the value is reflected in:

- parameter 306 [DC Bus Voltage] (700S)
- parameter 012 [DC Bus Voltage] (700H)

7. Make configuration changes which allow the HIM to issue start and speed commands.
8. Make configuration changes which allow operation without an encoder and motor.
9. Start the drive, by pressing
10.Increase the speed command from zero to base speed, by pressing (the up button).
11.Stop the drive, by pressing $\bigcirc$ (the stop button).
10. Return the configurations to suit the application.
13.Decrease the DC power supply output voltage to zero. Wait until DC bus voltage has decreased to zero. Switch off the external DC power supply.

## Testing Without a Motor

## Performing the Power

 Circuit Diagnostic Test on a 700SThis test allows you to measure several operating parameters and diagnose problems without connecting the motor.

1. Verify that input power wiring and grounding is connected.
2. Verify that the motor cables are disconnected.
3. Energize the drive.
4. Make configuration changes which allow the HIM to issue start and speed commands.
5. Make configuration changes which allow operation without an encoder and motor.
6. Start the drive, by pressing
7. Increase the speed command from zero to base speed, by pressing (the up button).
8. Measure the output voltage on each phase and verify that it is balanced. If it is unbalanced troubleshoot the drive.
9. Stop the drive, by pressing (the stop button).
10. Return the configurations to suit the application.

The Power Circuit Diagnostic Test, on the 700S, allow you to diagnose problems in the drive's power structure without applying large amounts of power.

1. Verify that input power wiring and grounding is connected.
2. Verify that the motor cables are connected.
3. Energize the drive.
4. From the Monitor menu on the HIM press Esc (the escape button) to navigate to the Main menu.
5. Use (the down button) to move the cursor to the Start-Up selection, and $\leftrightarrow$ to select Start-Up. Then press $\leftrightarrow$ again to verify your intention to continue with the Start-Up menu.
6. Use (the down button) to move the cursor to Power Circuit Diagnostics (Pwr Circuit Diag), and $\leftrightarrow$ to select Power Circuit Diagnostics.
7. Press to begin the Power Circuit Diagnostic routine. Follow indications and instructions on the HIM.

## Testing With the Motor

This test allows you to measure several operating parameters and diagnose problems without connecting the motor to its mechanical load.

1. Verify that input power wiring and grounding is connected.
2. Verify that the motor cables are connected.
3. Verify that the motor load is disconnected.
4. Energize the drive.
5. Start the drive and increase the speed from zero to base speed.
6. Measure drive output current and verify that the value is reflected in:

- parameter 308 [Output Current] (700S)
- parameter 003 [Output Current] (700H)

7. Stop the drive.

# Appendix $\boldsymbol{A}$ 

## Service Tools and Equipment

Software Tools

Service tools

DriveTools 2000, Drive Executive, Drive Explorer and Drive Observer are software tools for uploading, downloading and monitoring system parameters

Service of the PowerFlex frequency converter requires certain kinds of tools, devices and test equipment. Basic tools, devices and test equipment have to meet requirements of professional services. The tools have to be in good condition and have to fit how and where they are going to be used.

This list of basic service tools which will cover needs of tools for repair and maintenance measurements.

| Item | Description | Details |
| :---: | :---: | :---: |
| 1 | Oscilloscope | Portable, digitizing, dual channel scope, with isolation |
| 2 | Current clamp | 1000A(ac, rms), signal output |
| 3 | Soldering station | Soldering / de soldering |
| 4 | Adjustable power supply | $0 . . .1300 \mathrm{Vdc}, 1 \mathrm{~A}$, adjustable current limit. Efore LPS $750-\mathrm{HV}$ or equivalent. |
| 5 | Adjustable power supply | 0...690Vac (+10\%), 10A, three phase, galvanic isolation |
| 6 | Multi meter | Digital multi meter, capable of ac and dc voltage, continuity, resistance, capacitance measurements, and forward diode bias tests. Fluke model 87 III or equivalent. |
| 7 | Insulation tester | 1000 Vdc |
| 8 | Torque wrench | 1...12Nm |
| 9 | Torque wrench | 6...50Nm |
| 10 | box wrench | $7 \mathrm{~mm}, 8 \mathrm{~mm}, 10 \mathrm{~mm}, 13 \mathrm{~mm}, 17 \mathrm{~mm}, 19 \mathrm{~mm}, 22 \mathrm{~mm}$ |
| 11 | socket extension | 230 mm |
| 12 | Wrench | $7 \mathrm{~mm}, 8 \mathrm{~mm}, 10 \mathrm{~mm}, 13 \mathrm{~mm}, 17 \mathrm{~mm}, 19 \mathrm{~mm}, 22 \mathrm{~mm}$ |
| 13 | Wire cutter |  |
| 14 | Nose pliers |  |
| 15 | Crimping tools | For cable terminals 1,5...240 |
| 16 | Angle wrench |  |
| 17 | Screw driver |  |
| 18 | *Flat nose | 7*2(mm) |
| 19 | *Pozidrive | 1, 2, 3 |
| 20 | *Phillips | 1,2,3 |
| 21 | *Torx | 25 |
| 22 | Hexagonal wrench | 4, 5, 6 |
| 23 | ESD-protected place of work | Working surface, Floor covering, seat and earthings |
| 24 | ESD-protective clothing | Wrist wrap, shoes, overall clothing (coat) |
| 25 | Power supply (service) | Capacity of three phase service 400/500/690Vac, 250A |


| Item | Description | Details |
| :--- | :--- | :--- |
| 26 | CK-2 | Cable kit of DC power supply for PowerFlex frame 9 <br> units |
| 27 | RT-1 | Module replacement tool for PowerFlex frame 9 units |
| 28 | Fiber-optic repair kit |  |

## Schematics




[^0]




Figure B. 7 Circuit Board Connections for
700H Drives


# ${ }_{\text {Appendix }}$ C 

## Disassembly / Assembly Diagrams

Diagrams on the following pages illustrate disassembly and assembly of the drive and its sub-systems.
Figure C. 1 700S 261A / 300A Mechanical Construction

Figure C. 2 700H 261A / 300A Mechanical Construction








Figure C. 9 Power Module


## Key to ID Numbers

The following table describes the parts identified by balloons in the mechanical drawings:

| Id. No. | Description | Shown in... |
| :---: | :---: | :---: |
| 2 | DC Bus Capacitor ELKO 3300uF 420V | Figure C.5 |
| 3 | Fan 230W | Figure C. 6 |
| 5 | AC-choke/filter 310A | Figure C.1, Figure C. 2 |
| 6 | Frame | Figure C.1, <br> Figure C. 2 |
| 8 | Cover (power) | Figure C.1, Figure C. 2 |
| 9 | Cover (connection) | Figure C.1, Figure C. 2 |
| 10 | Bushing plate | Figure C.1, <br> Figure C. 2 |
| 12 | Earthing plate | Figure C.2 |
| 15 | Earthing cover 3 | Figure C.1, Figure C. 2 |
| 20 | Screw M4 x 8 | Figure C. 3 |
| 23 | Upper plate | Figure C.1, Figure C. 2 |
| 26 | Busbar DC- and brake | Figure C.1, Figure C. 2 |
| 28 | Rectifying board | Figure C. 8 |
| 29 | Diode mod SKKH 330/16 | Figure C. 8 |
| 30 | IGBT/Diode SKM 195GAL123D (brake) | Figure C. 8 |
| 31 | Stand-off insulator M6*25 (brake) | Figure C.1, Figure C. 2 |
| 32 | Busbar DC connection | Figure C. 5 |
| 34 | Busbar DC+ | Figure C. 5 |
| 35 | Insulator DC+/- | Figure C. 5 |
| 36 | Busbar DC- | Figure C. 5 |
| 38 | Capacitor 220nF/1250V 500 V 6 mm | Figure C. 8 |
| 39 | Discharging resistor 2x8k | Figure C. 6 |
| 40 | Rectifying module sub-as. | Figure C.1, Figure C. 2 |
| 40 | Rectifying module sub-as. (brake) | Figure C.1, Figure C. 2 |
| 41 | Fan plate | Figure C. 6 |
| 42 | Screw M6 x14 Z4-1 (combination) | Figure C.5, Figure C.8, Figure C. 9 |
| 44 | Screw M6 x16 Z4-1 (combination) | Figure C.5 |
| 45 | Screw M5x20 TX (combination) | Figure C.5, Figure C. 8 |
| 52 | Washer (straight) M8 SFS3738 | Figure C.5, Figure C.8, Figure C. 9 |
| 53 | Washer (cone) M8 DIN679 | Figure C.5, Figure C.8, Figure C. 9 |
| 54 | Screw hexagonal M8 X 20 | Figure C.5, Figure C.8, Figure C. 9 |
| 55 | Screw M4 x 8 | Figure C. 6 |
| 59 | Bushing rubber GD21 | Figure C.1, Figure C. 2 |


| Id. No. | Description | Shown in... |
| :---: | :---: | :---: |
| 63 | Control bracket | Figure C.1, Figure C.2, Figure C. 7 |
| 64 | EMC-protection plate (power) | Figure C.1, <br> Figure C.2, <br> Figure C. 4 |
| 66 | Cable lug KP40 | Figure C.1, Figure C. 2 |
| 68 | Fan power supply |  |
| 69 | Internal fan | Figure C.3, Figure C. 4 |
| 70 | Cross plate (terminals) | Figure C.1, <br> Figure C.2, <br> Figure C. 3 |
| 75 | Control frame | Figure C.1, <br> Figure C. 2 |
| 81 | Screw M4 x 8 | Figure C. 8 |
| 83 | Control cable conduit | Figure C.1, Figure C. 2 |
| 84 | Plate gasket 52486 | Figure C.1, Figure C. 2 |
| 85 | Bushing rubber 52515 | Figure C.1, Figure C. 2 |
| 86 | Cover (control cable conduit) | Figure C.1, Figure C. 2 |
| 88 | Terminal sub-assembly H | Figure C.1, Figure C. 2 |
| 88 | Terminal sub-assembly T/L | Figure C.1, Figure C. 2 |
| 89 | Fan sub-assembly | Figure C.1, Figure C. 2 |
| 90 | Stop plate 34 | Figure C.1, Figure C. 2 |
| 91 | Bushing rubber GD9 | Figure C.1, <br> Figure C. 2 |
| 92 | Capacitor sub-Assembly | Figure C.1, <br> Figure C. 2 |
| 93 | Heat sink (rectifying module) | Figure C. 8 |
| 94 | Frame (heat sink, rectifier) | Figure C. 8 |
| 95 | Busbar rectifying board | Figure C. 8 |
| 96 | Busbar rectifier + | Figure C. 8 |
| 97 | Insulator, rectifier | Figure C. 8 |
| 98 | Busbar rectifier - | Figure C. 8 |
| 99 | Busbar brake | Figure C. 8 |
| 100 | Bushing rubber GD16 | Figure C. 6 |
| 102 | Clamp for ferrite ring | Figure C. 4 |
| 103 | Ferrite ring packet | Figure C.1, Figure C.2, Figure C. 4 |
| 104 | VaconBus adapter | Figure C. 7 |
| 105 | Finger proof shield | Figure C. 3 |
| 109 | Insulator capacitor | Figure C. 5 |
| 110 | Insulator DC-/connection | Figure C. 5 |


| Id. No. | Description | Shown in... |
| :---: | :---: | :---: |
| 112 | Cable DC+ | Figure C. 5 |
| 114 | Cable DC- | Figure C.5 |
| 115 | Screw M5 x 10 | Figure C. 9 |
| 116 | Fan power supply cover | Figure C.1, Figure C. 2 |
| 117 | Power module sub-as. 261A | Figure C.1, Figure C.2, Figure C. 9 |
| 117 | Power module sub-as. 300A | Figure C.1, Figure C.2, Figure C. 9 |
| 118 | Bushing rubber GD48 | Figure C.1, Figure C. 2 |
| 200 | 700S Control Assembly | Figure C.1, |
| 201 | 700S Voltage Feedback Circuit Board | Figure C.1, |
| 202 | 700S Power Interface Circuit Board | Figure C.1, |
| 203 | DPI / HIM Assembly | Figure C.1, Figure C. 2 |
| 204 | MOV | Figure C.1, Figure C. 2 |
| 205 | Fan (Control frame) | Figure C. 1 |
| 206 | 700H Control Assembly | Figure C. 2 |

## Power, Control and Information Solutions Headquarters

Americas: Rockwell Automation, 1201 South Second Street, Milwaukee, WI 53204-2496 USA, Tel: (1) 414.382.2000, Fax: (1) 414.382 .4444 Europe/Middle East/Africa: Rockwell Automation, Vorstlaan/Boulevard du Souverain 36, 1170 Brussels, Belgium, Tel: (32) 2 663 0600, Fax: (32) 26630640 Asia Pacific: Rockwell Automation, Level 14, Core F, Cyberport 3, 100 Cyberport Road, Hong Kong, Tel: (852) 2887 4788, Fax: (852) 25081846


[^0]:    Figure B. 2 Power Circuitry for 700S
    Drives with AC Input

